



OPTIMIZATION AND AMPLIFICATION OF CACHE SIDE CHANNEL SIGNALS

DAVID KAPLAN, SECURITY ARCHITECT

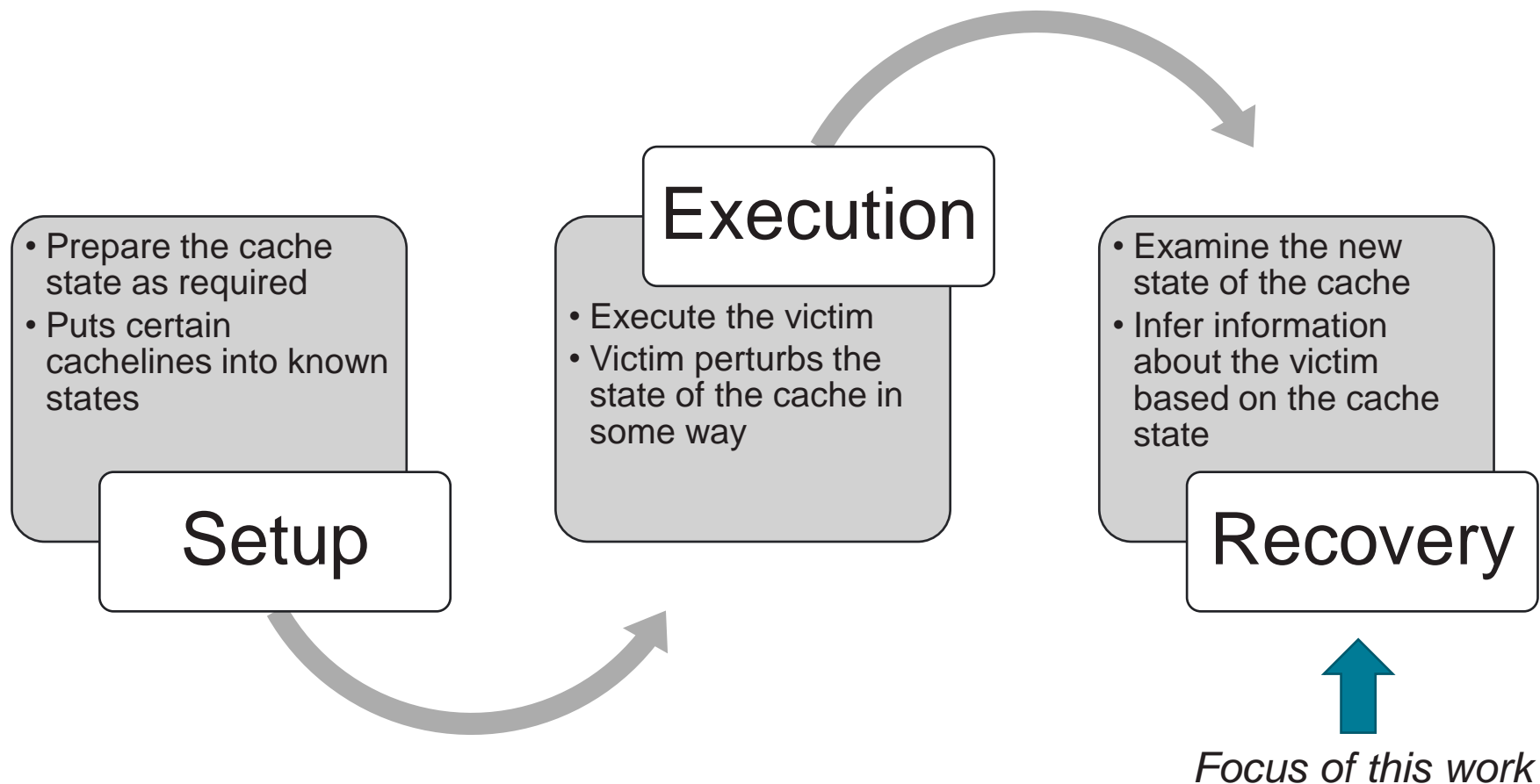
JUNE 2022

NOTICE

- The work described in this presentation is my own
- Independently, very similar work was developed by:
 - Daniel Katzman*, William Kosasih^, Chitchanok Chuengsatiansup^, Eyal Ronen*, and Yuval Yarom^
 - Their work is entitled “The Gates of Time” (under submission)
- I am working with this group to merge our findings into a joint paper

* Tel-Aviv University
^ The University of Adelaide

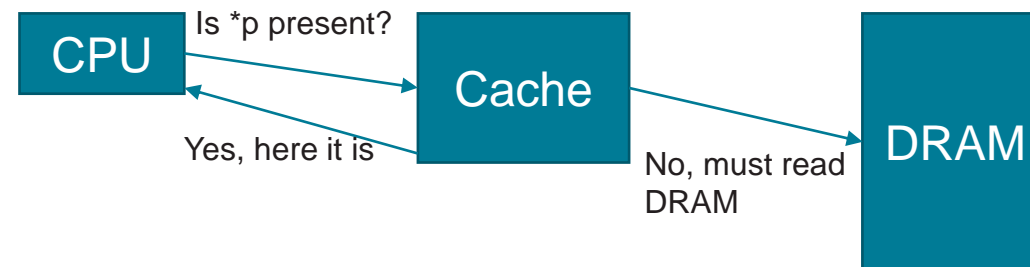
SIDE CHANNEL BASICS



READING A “SIGNAL”

- A “signal” refers to the state of a particular cacheline
- Reading a “signal” is typically done using a high precision timer
- Typical timer: CPU Time Stamp Counter (TSC)
 - Present cacheline: ~50 cycles
 - Not-Present cacheline: ~280 cycles
 - Difference is measured in nanoseconds
- Meaning of the signal varies based on the attack
 - FLUSH+RELOAD: Looks for a line to be present
 - PRIME+PROBE: Looks for a line to not be present

```
t1 = rdtscp();  
x = *p  
t2 = rdtscp();  
time = t2-t1;
```



QUESTIONS

- Do I need a high precision timer to read a signal?
- Do I need at least a reasonably high precision (<1ms) timer to read a signal?
- Do I need to time N accesses to check the state of N cachelines?

Answer: NO

BASIC PRIMITIVE

- Let's start with 2 cachelines, A and B
 - State of A is initially unknown
 - B is initially not present
 - Value of memory at A is 0
- Further, let's assume the branch is mis-predicted (incorrectly taken)
- How long it takes the CPU to realize the misprediction depends on the state of A
 - If A was initially present, it takes a short amount of time to realize the misprediction => B is not fetched
 - If A was initially not-present, it takes a long amount of time => B is fetched
- Notice that the state of B is therefore the *inverse* of the state of A after execution

```
if (*A !=0)
    Access line B
```

IMPLEMENTING THE INVERTER

How do we force the CPU to mis-predict?

```
1: call 3f
2: #Speculative instructions go here
   lfence
3: mov $4f, (%rsp)
   ret
4: nop
```

The CPU *usually* predicts that RET instructions return to the instruction after a CALL

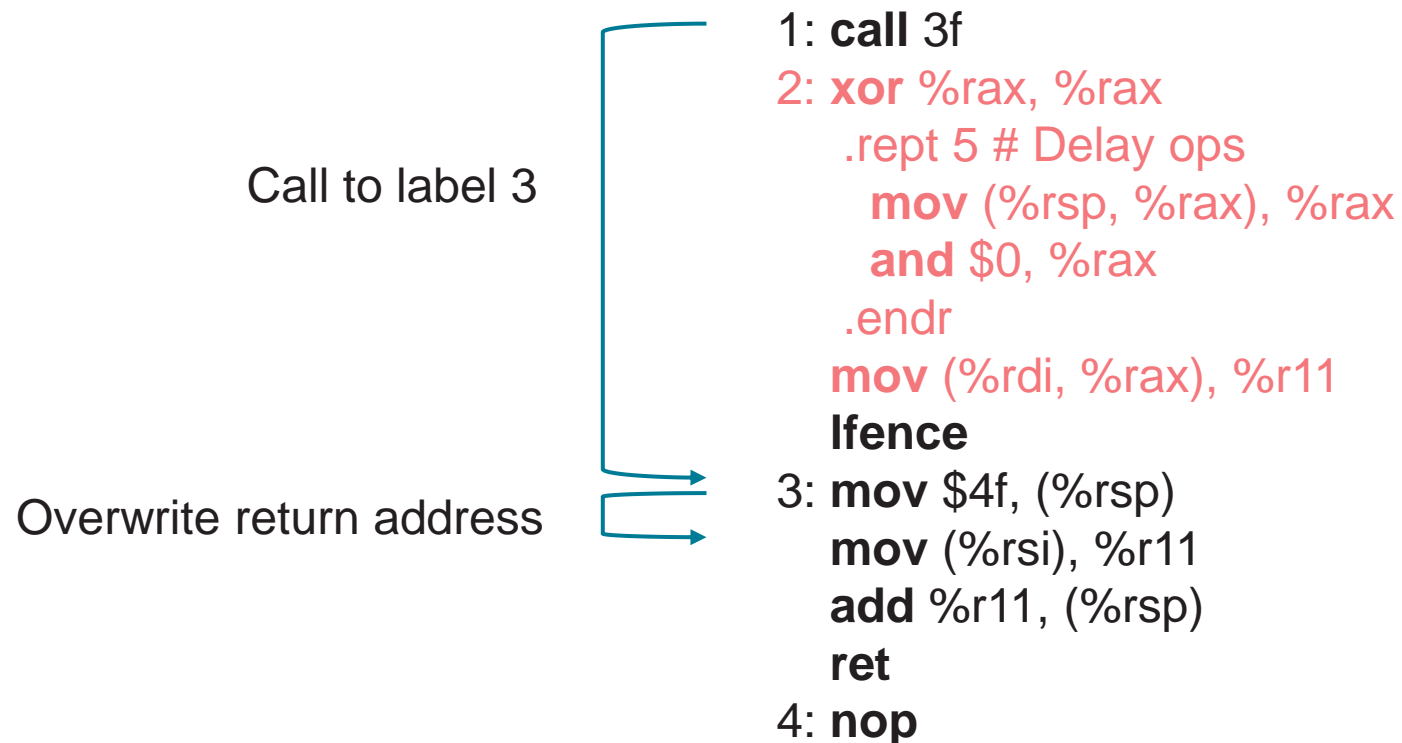
But in this code, it overwrites the return address on the stack with label 4

Architectural flow: 1->3->4

Speculative flow: 1->3->2

IMPLEMENTING THE INVERTER

RSI = cacheline A
RDI = cacheline B



IMPLEMENTING THE INVERTER

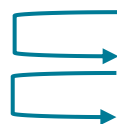
RSI = cacheline A
RDI = cacheline B

```

1: call 3f
2: xor %rax, %rax
   .rept 5 # Delay ops
   mov (%rsp, %rax), %rax
   and $0, %rax
   .endr
   mov (%rdi, %rax), %r11
lfence
3: mov $4f, (%rsp)
   mov (%rsi), %r11
   add %r11, (%rsp)
   ret
4: nop

```

Read cacheline A
 Add the result (0) to the
 return address on the top
 of the stack



IMPLEMENTING THE INVERTER

RSI = cacheline A
RDI = cacheline B

Mis-speculate to here

```
1: call 3f
2: xor %rax, %rax
   .rept 5 # Delay ops
   mov (%rsp, %rax), %rax
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   .endr
   mov (%rdi, %rax), %r11
lfence
3: mov $4f, (%rsp)
   mov (%rsi), %r11
   add %r11, (%rsp)
   ret
4: nop
```

IMPLEMENTING THE INVERTER

RSI = cacheline A

RDI = cacheline B

Execute delay ops

This gives the CPU time
to resolve the RET if A
was present

1: **call** 3f

2: **xor** %rax, %rax

.rept 5 # Delay ops

mov (%rsp, %rax), %rax

and \$0, %rax

.endr

mov (%rdi, %rax), %r11

lfence

3: **mov** \$4f, (%rsp)

mov (%rsi), %r11

add %r11, (%rsp)

ret

4: **nop**

IMPLEMENTING THE INVERTER

RSI = cacheline A

RDI = cacheline B

If A was not present,
we'll reach here and
access cacheline B

1: **call** 3f

2: **xor** %rax, %rax

.rept 5 # Delay ops

mov (%rsp, %rax), %rax

and \$0, %rax

.endr

mov (%rdi, %rax), %r11

lfence

3: **mov** \$4f, (%rsp)

mov (%rsi), %r11

add %r11, (%rsp)

ret

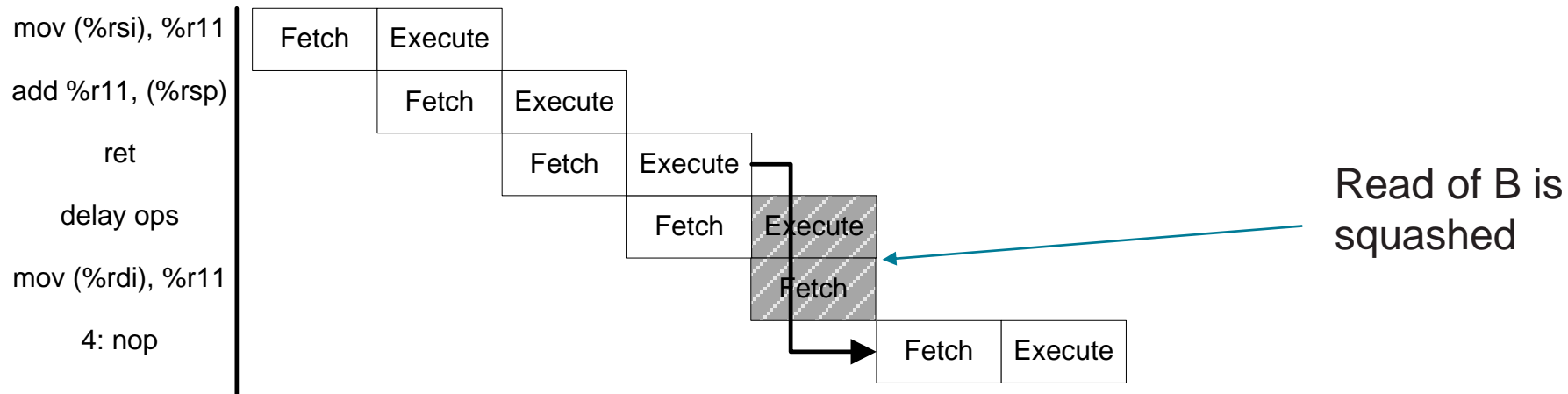
4: **nop**



INVERTER EXPLAINED

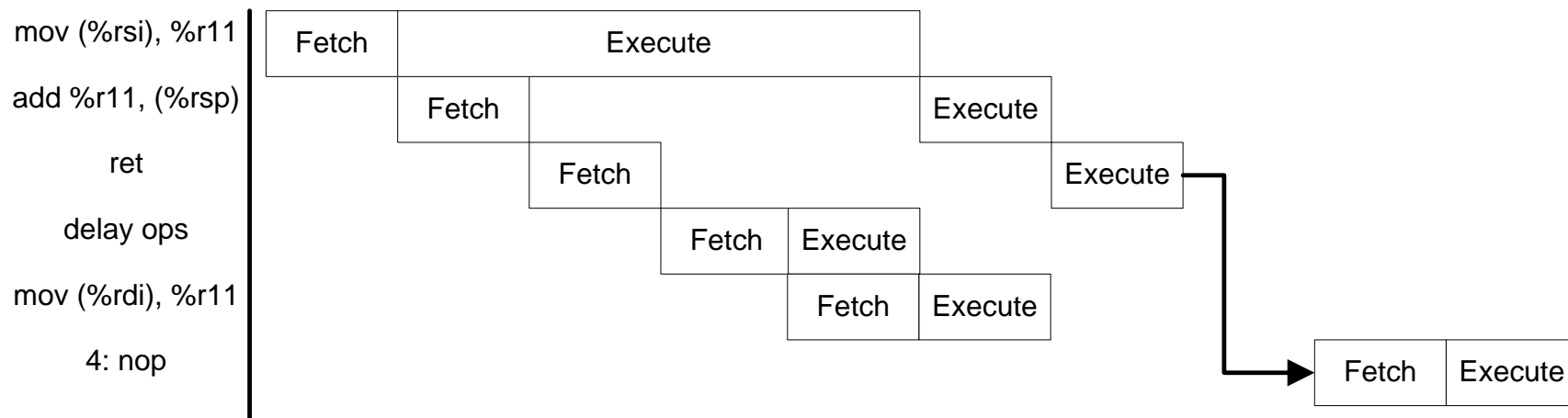
A is present

The read of %RSI
executes quickly



A is NOT present

The read of %RSI
executes slowly



HOW ABOUT THIS CODE

This code reads 2 cachelines (RSI and RDX)

Notice there is a dependency: The **add** instructions cannot execute until R11 is computed

Therefore:

(%RSI)	(%RDX)	Output (%RDI)

1: **call** 3f

2: **<delay ops>**

mov (%rdi, %rax), %r11

lfence

3: **mov** \$4f, (%rsp)

mov (%rsi), %r11

add (%rdx), %r11

add %r11, (%rsp)

ret

4: **nop**

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Not present	Not present	Present

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4: **nop**

HOW ABOUT THIS CODE

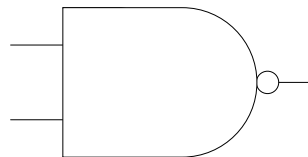
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Therefore:

(%RSI)	(%RDX)	Output (%RDI)
Not present	Not present	Present
Not present	Present	Present
Present	Not present	Present
Present	Present	Not Present

NAND!



1: **call** 3f

2: **<delay ops>**

mov (%rdi, %rax), %r11

lfence

3: **mov** \$4f, (%rsp)

mov (%rsi), %r11

add (%rdx), %r11

add %r11, (%rsp)

ret

4: **nop**

MORE GADGETS

- **Replicator**
 - Sets the state of N cachelines equal to the opposite of the input
 - Basically an inverter with multiple output lines
- **NOR Gadget**
 - Exercise for the reader 😊
- **Multi-input gadgets**
 - Simple 2-input NAND (and NOR) gadgets can be trivially expanded to take multiple inputs
 - There is practical limit on fan-in and fan-out based on CPU capabilities
- Note that we always assume cachelines have the value 0
 - The memory is attacker-controlled, and therefore can have attacker-controlled values (0 being easiest)
 - The attacker is only interested in the presence of the cacheline, not its value

SIGNAL AMPLIFICATION



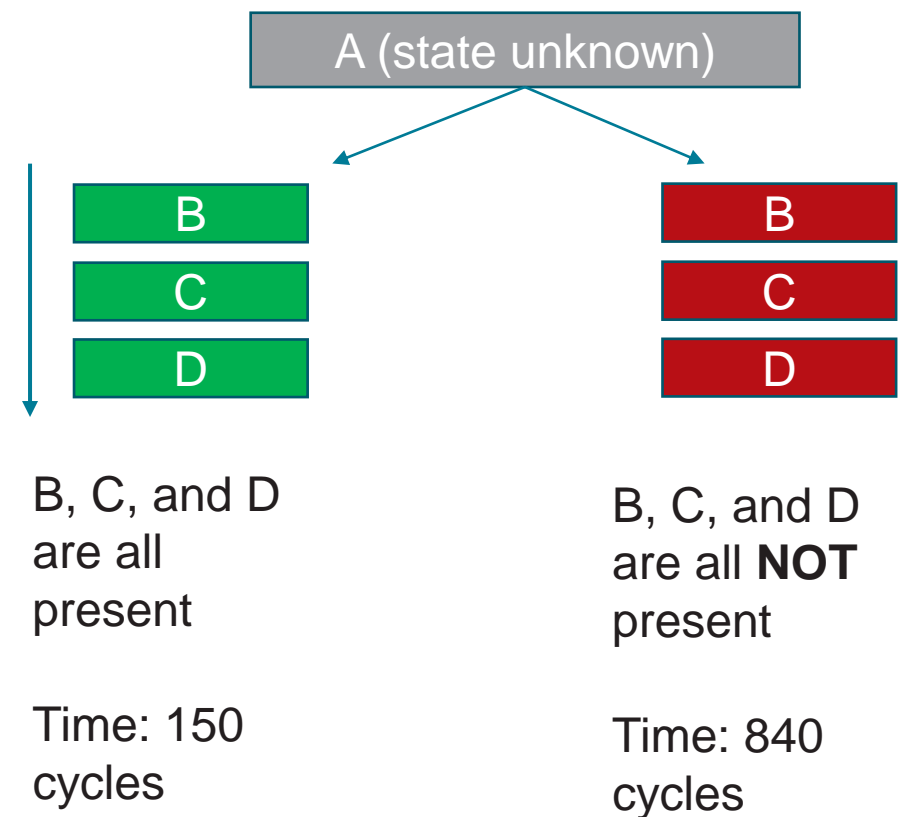
AMPLIFIER GOALS

- Given a single cacheline A in an unknown state, how can we conduct a measurement to determine the state of the line with a low precision timer?
- Our plan is to execute some code and then conduct a timing measurement
 - If A was initially present, the time measured will be T1
 - If A was initially not present, the time measured will be T2
 - We want to make $|T2-T1|$ be as large as possible
- ***Signal strength = $|T2-T1|$***
- For a single cacheline, for example:
 - T1 = 50, T2 = 280
 - ***Signal strength = 230 cycles***

```
t1 = rdtscp();  
x = *p  
t2 = rdtscp();  
time = t2-t1;
```

SINGLE-STAGE AMPLIFIER

- The single-stage amplifier consists of two parts:
 - 1:N replicator**
 - This uses the replicator gadget to access many cachelines if the input cacheline is not present
 - The replicator will attempt to fetch all N lines *in parallel*
 - N will vary by CPU architecture. On AMD Zen3, N=23 worked well
 - Timing measurement**
 - This code will access all N lines *in series* and time how long this takes
 - Use a data dependency to force the processor to access all N lines, one at a time



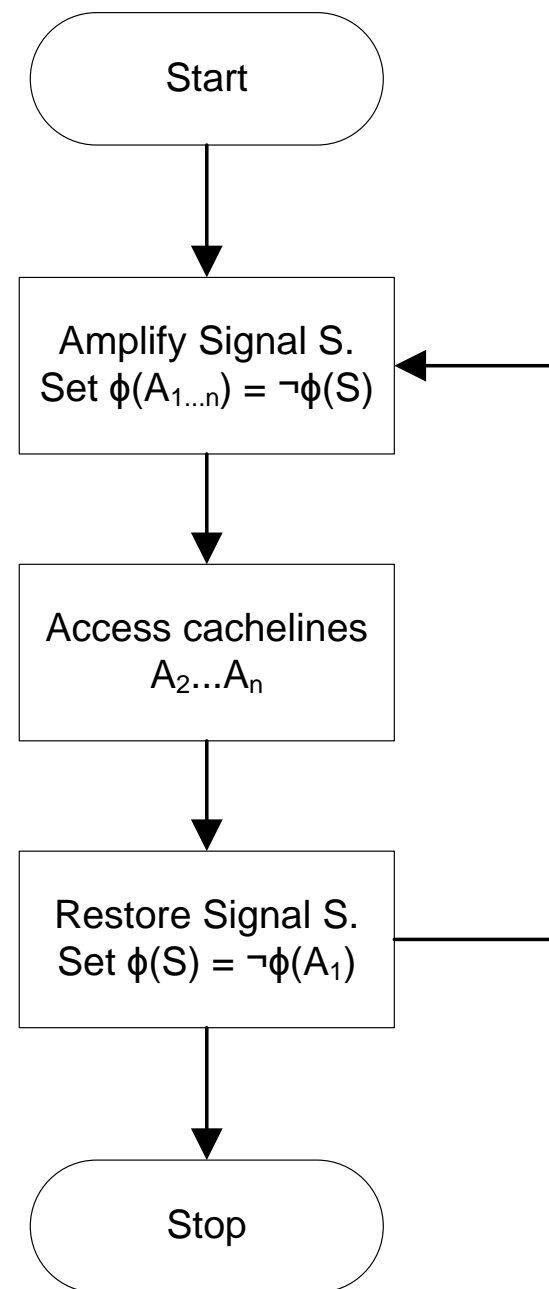
$$\text{Signal strength} = 840 - 150 = 690$$

BEYOND SINGLE-STAGE

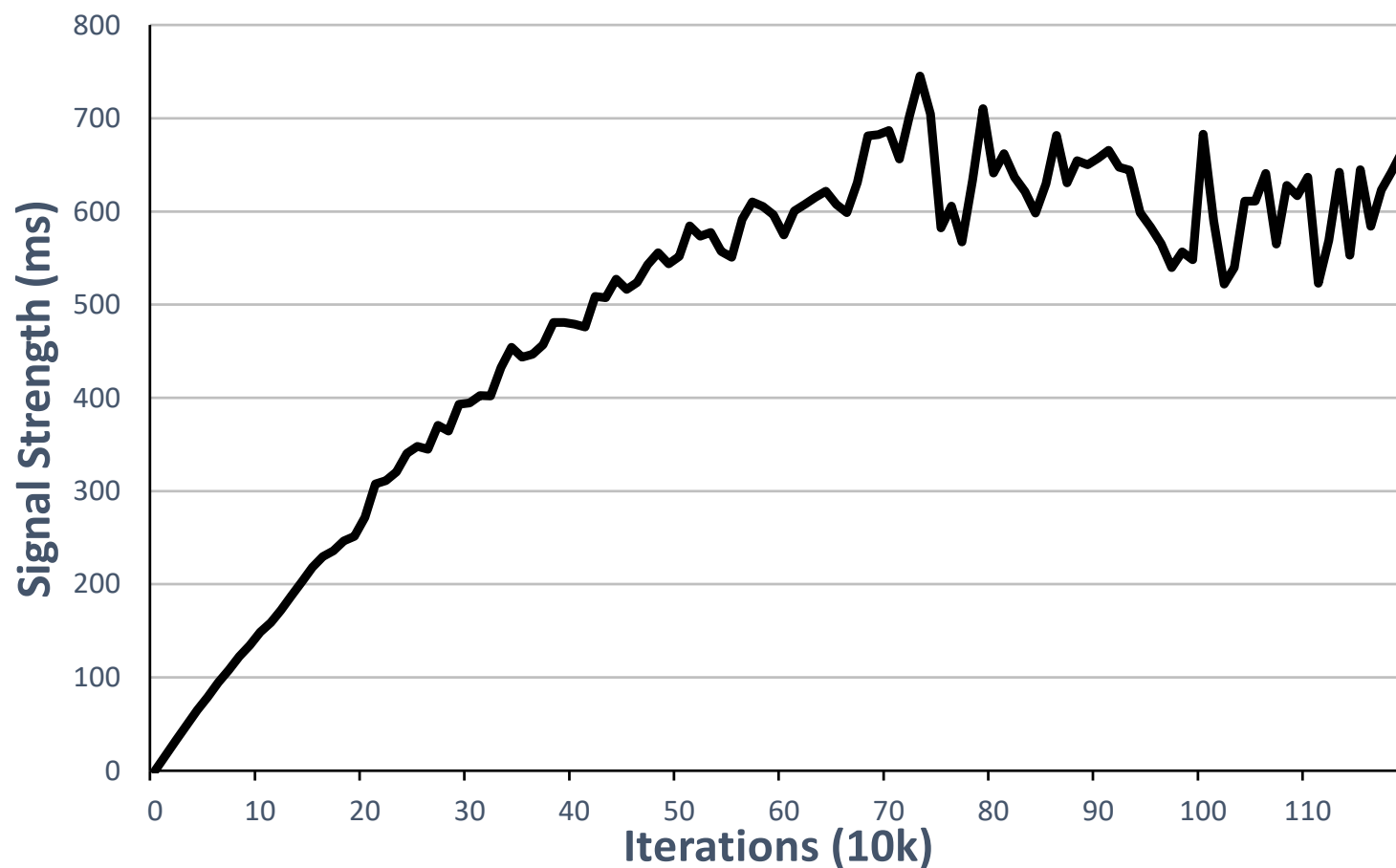
- The single stage amplifier is limited by the 1:N replicator gadget
 - Achieves amplification of $\sim N$ times
- Can we just chain these together?
 - First stage: Set the state of N cachelines based on the initial cacheline
 - Second stage: Set the state of $N*N$ cachelines based on the N cachelines from the first stage
 - Third stage: Set the state of $N*N*N$ cachelines based on the $N*N$ cachelines from the second stage
 - Etc.
- In theory, this could enable much higher amplification. But it runs into practical problems:
 - The size of the cache is limited...entire cache is consumed after 5th stage
 - Other system interference creates additional noise

CAN WE DO BETTER?

- The Self-Reinforcing Amplifier is even better
- Idea:
 - Use the single-stage amplifier but save one cacheline behind
 - E.g. replicate input to 23 cachelines, but only time access to 22
 - Use the saved cacheline to restore the state of the input line
 - Rinse and repeat
- In diagram, $\Phi(X)$ means X is present in the cache
- Key point:
 - The 1:N replicator accesses all N lines in parallel
 - The access of lines $2\dots N$ is then done in series



RESULTS



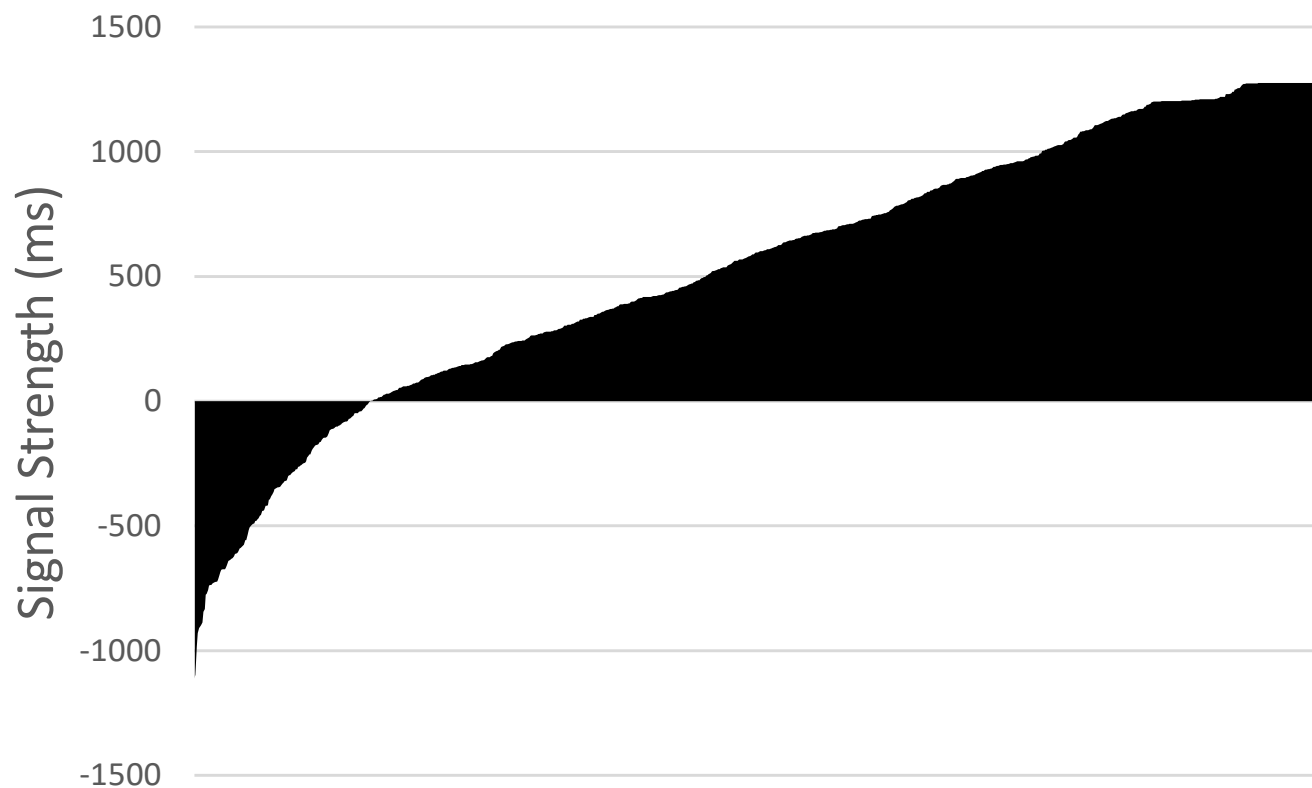
Signal strength increases consistently but only up to a point

With each iteration, there is a risk of signal corruption

700k looks like a good choice

700K AMPLIFIER

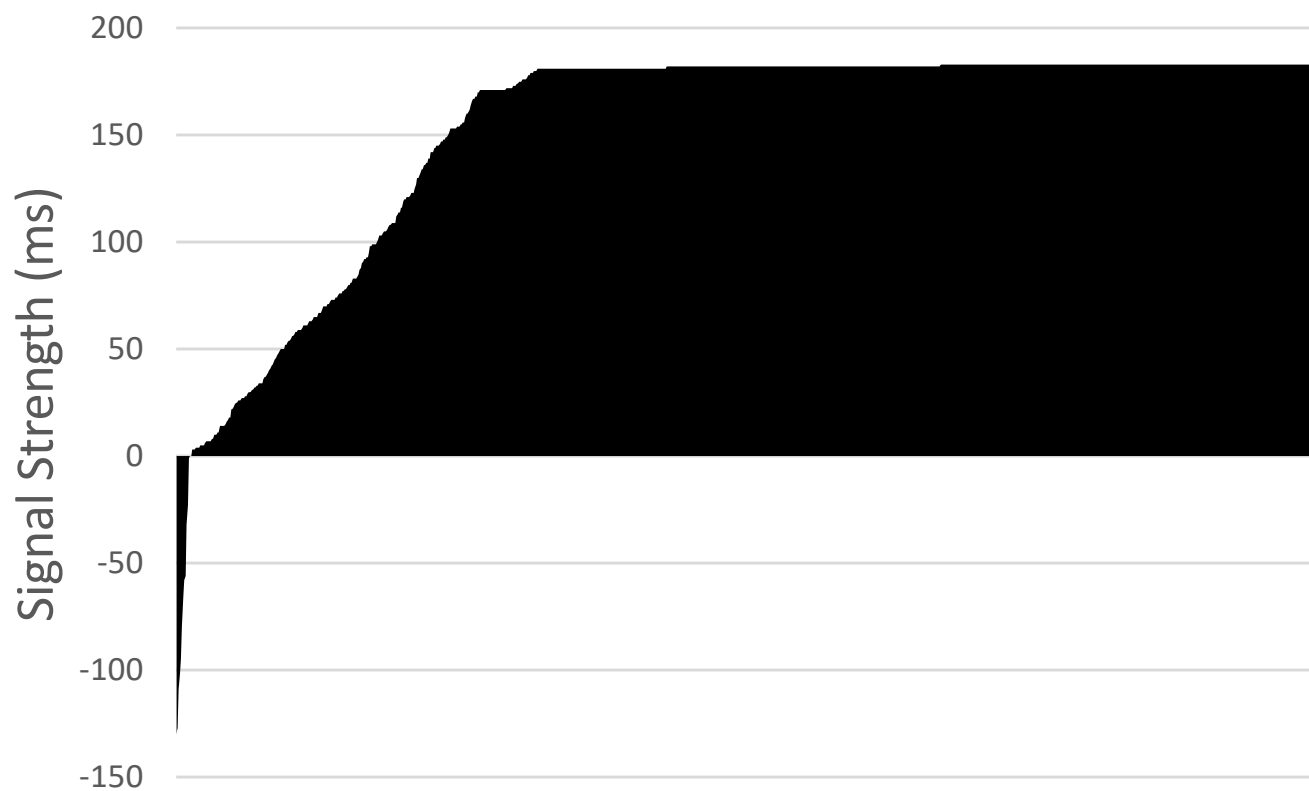
- Chart shows results from 1000 runs
- Average signal strength was ~600ms
- Can recover the state of the initial line with ~50% chance with a 500ms timer
 - And 40% of indeterminate signal
- With a 100ms timer, correct signal retrieved 66% of the time
- Note: Negative signal strengths indicate incorrect recovery



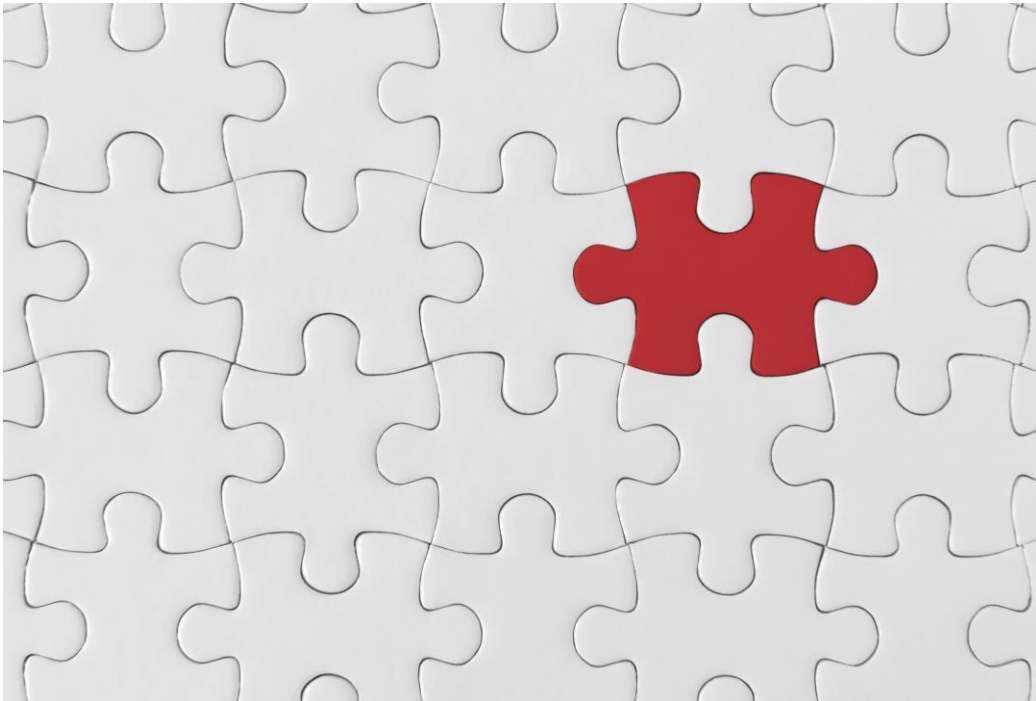
100K AMPLIFIER

- 100k is a better choice if a slightly better time is available
- Average signal strength: 182ms
- 82% chance of correct recovery with a 100ms timer
 - And only 1% chance of incorrect recovery
- 95% chance of correct recovery with a 10ms timer

- 182ms is >2M amplification compared to baseline



MORE FUN WITH CACHELINES

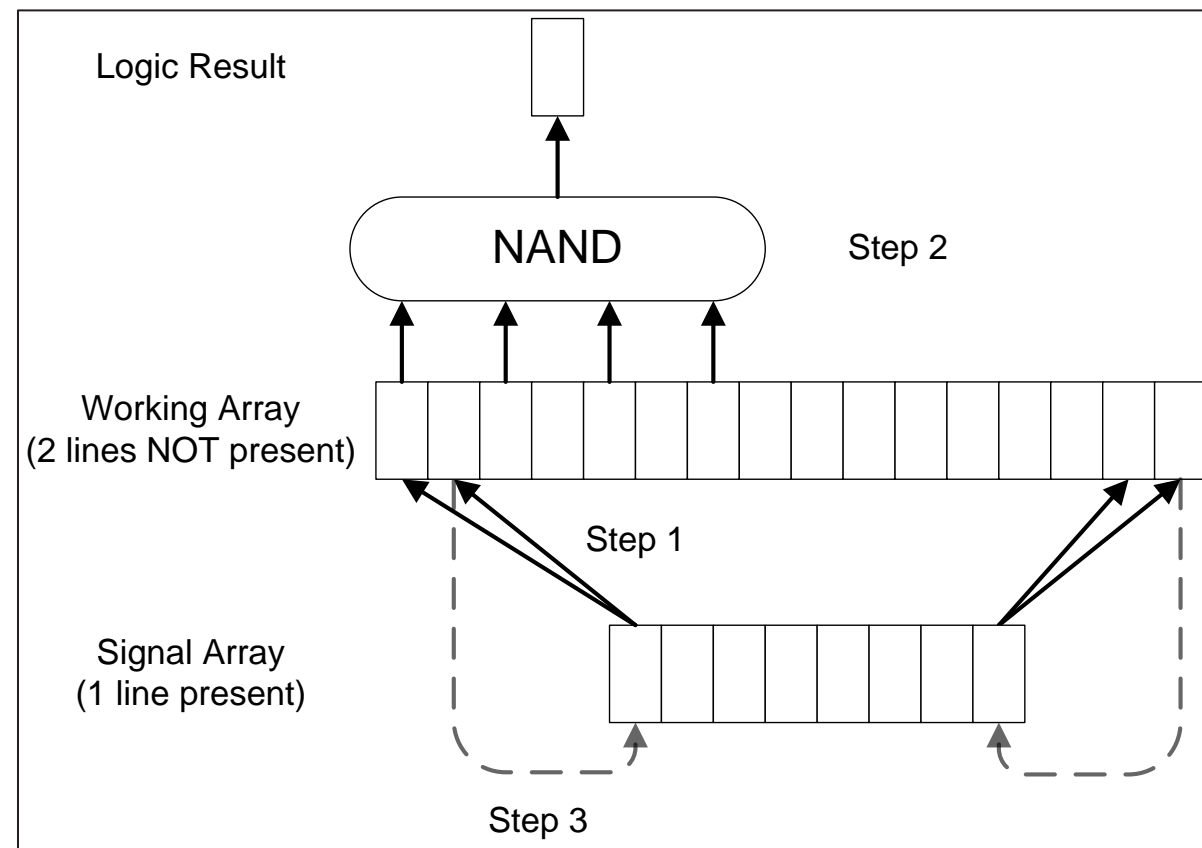


BINARY SEARCH

- **Given N cachelines of which exactly 1 is present, determine which cacheline is present using the fewest timing measurements as possible**
- Useful for side channel attacks where an array is indexed with a secret
 - E.g. FLUSH+RELOAD attack where victim executes $x = \text{array}[\text{secret}]$
 - Goal is to determine which $\text{array}[]$ line was brought in
- Binary search seems like a good choice, but how can we do it without losing state?
 - Every time a gadget is used, it will bring in the source cacheline
 - We must find a way to preserve the initial state of the entire array before doing our search

BINARY SEARCH

- **1. 1:2 Replicator**
 - For each line in signal array, set two lines in the working array to be the inverse
 - **2. NAND Gadget**
 - Perform a multi-input NAND of lines corresponding to half the signal array
 - E.g. 4-input NAND from an 8-wide initial array
 - **3. Inverter**
 - For each untouched line in the working array, restore the original signal array
- If NAND result is 1, the present line is in that half
 - Only timing measurement is needed on NAND result



BINARY SEARCH RESULTS

- Different sizes were tested, with the present cacheline being selected randomly
- Number of timing measurements= $\text{Log}_2(\text{Size})$
- Note: Goal of binary search is to minimize number of timing measurements, *not* to maximize speed
 - Binary search ~15-20x slower than simple method of testing each cacheline individually

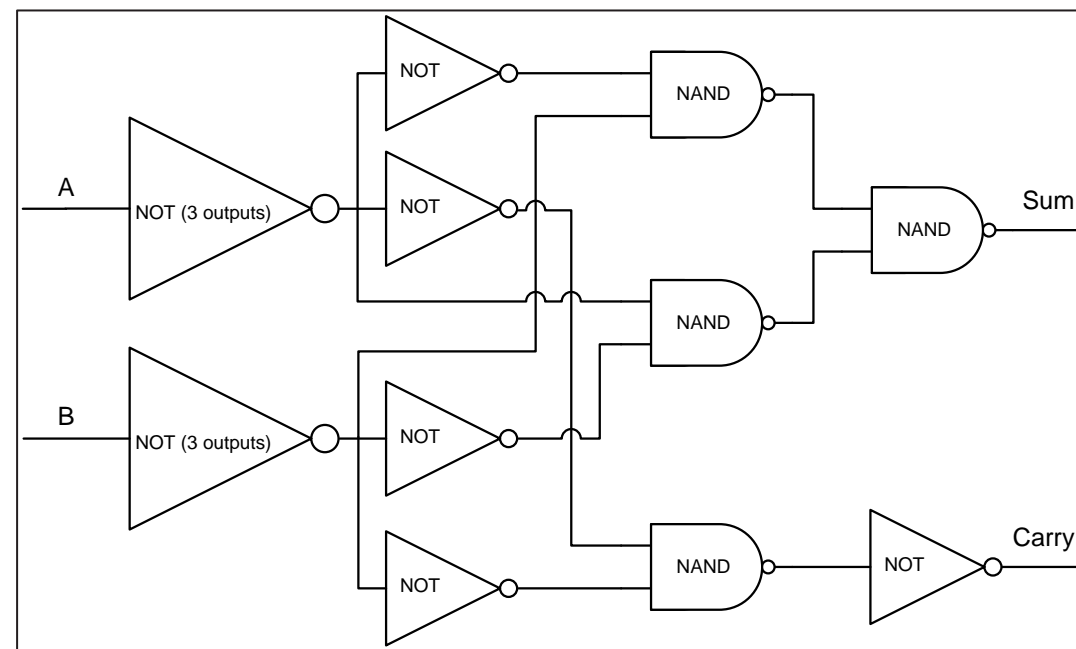
Size	Accuracy (100k runs)
4	100%
8	100%
16	100%
32	100%
64	99.99%
128	92.37%
256	66.40%

CACHELINE COUNTER

- **Given N cacheline in unknown state, count the number of present cacheline using as few timing measurements as possible**
- May be useful if the attacker is trying to infer which code path a victim took
 - E.g. in one code path, the victim touches 5 lines, while in another, it touches 7
 - Useful in PRIME+PROBE to count number of evicted lines
- We need a counter...but not exactly a traditional one

CACHELINE COUNTER

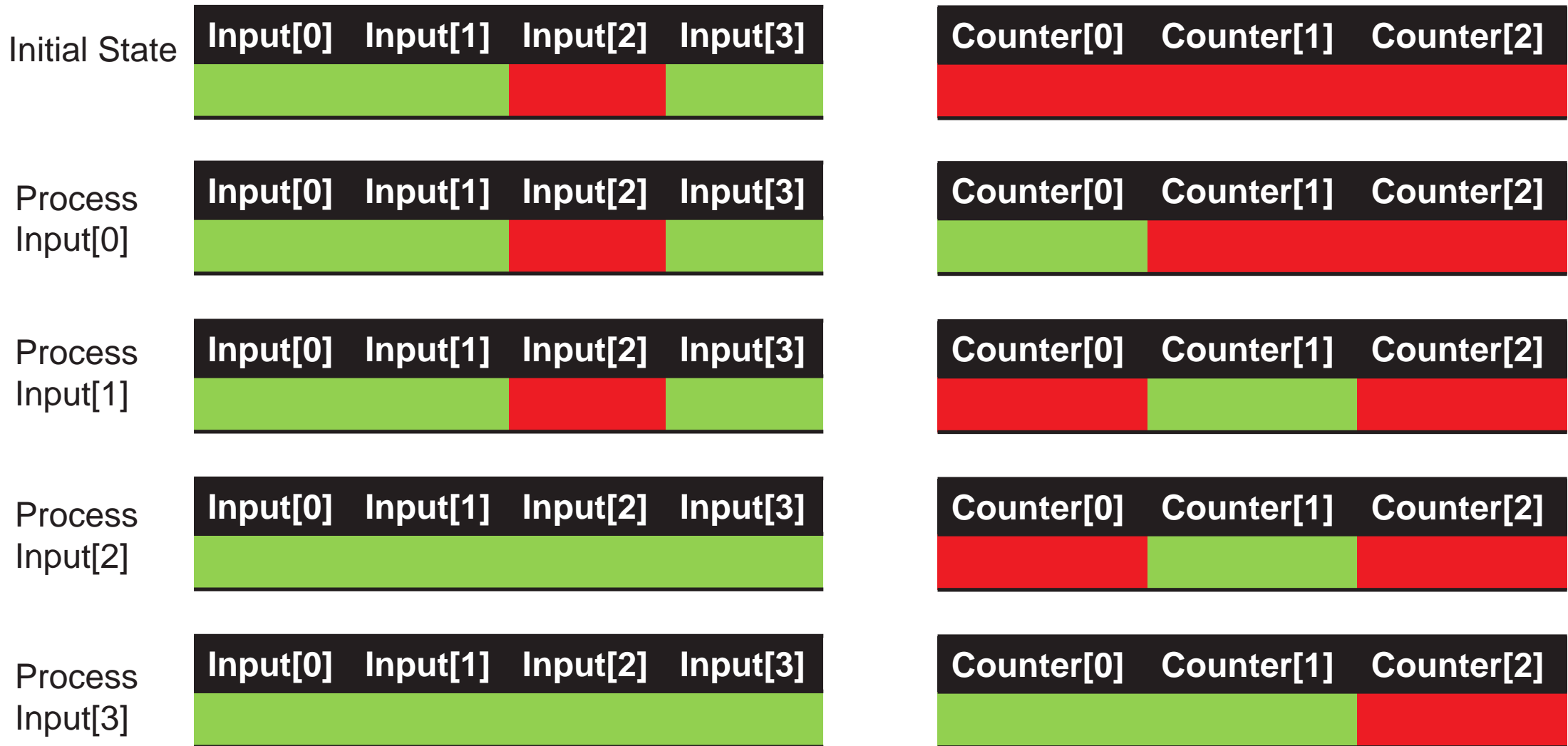
- The state of our counter will be stored in the ***presence of a set of cachelines***
 - Example: 32 entry array of potentially present cachelines
 - Attacker allocates 6 new cachelines, where each corresponds to a bit of an adder
 - E.g. if the counter is 6'b001101 then
 - Cache_Counter[0], [2], and [3] are present
 - Cache_Counter[1], [4], and [5] are not present
- Initially, all cachelines corresponding to the counter are not present (counter=0)
- We then “add” each input cacheline into our counter



Present

Not Present

COUNTER EXAMPLE (SIZE 4)



COUNTER RESULTS

- Different sizes were tested, with randomized initial configurations
- Number of timing measurements needed= $\text{Log}_2(\text{Size}+1)$
 - Only need to read the state of the cachelines corresponding to the counter at the end
- High accuracy across all tested sizes
 - Doesn't have large fan-in/fan-out gadgets

Size	Accuracy (100k runs)
4	99.99%
8	99.98%
16	99.94%
32	99.84%
64	99.70%
128	98.28%
256	97.98%

CONCLUSION

KEY TAKEAWAYS

Disabling high precision timers is a weak mitigation for side channel attacks

- As shown, signal amplification works and can result in signal strengths easily measurable by extremely coarse timers
- All results shown were based on a single cacheline from a single run. If the victim can be invoked multiple times, accuracy will skyrocket

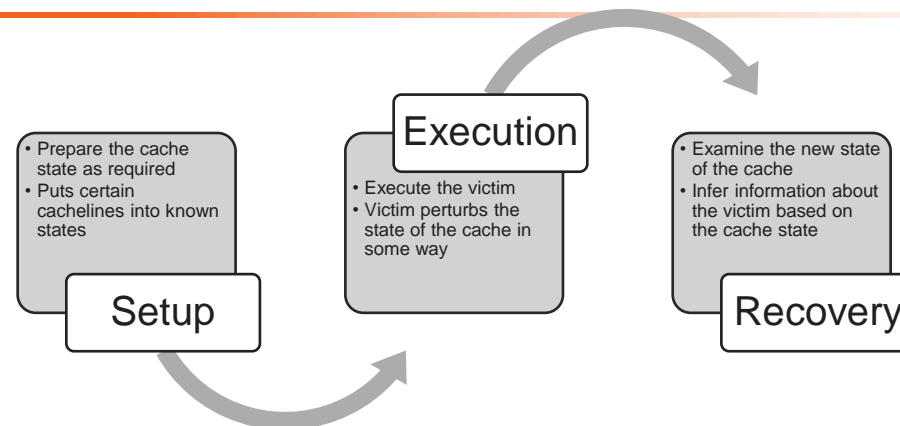
Monitoring access to timers is also a weak mitigation

- First off, signal amplification can make it such that such timers are not needed often
- And using logic gadgets to manipulate cache signals before reading can greatly reduce the number of measurements needed

Signals can be computed on before measurement

- Performing logical operations like binary searches could improve performance if every measurement requires significant amplification

MITIGATIONS



- This work is (to my knowledge) one of the first to focus on the signal recovery aspect of side channel attacks
- But if the attack is not able to get to the signal recovery stage, no extra mitigations are needed
- Mitigations are most effective at preventing the attack in the first place
 - Fences to prevent unwanted speculation
 - Non-secret dependent memory accesses
 - Etc.
- Even though timer restrictions are clearly ineffective, they can still be a defense-in-depth measure

FUTURE WORK

- There are likely more types of gadgets and interesting use cases
- Can errors be minimized and/or corrected when doing these operations?
- Can amplifiers be improved beyond what was shown?
- Does storing state in the presence of cachelines become a computing paradigm?
 - State stored in the presence of cachelines cannot be viewed without perturbing it
 - Could this be a way to detect side channel attacks?

- Keep an eye out for the paper by Katzman, et al.

Questions?

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